Constraints on Macrorealism Without Non-Invasive Measurability

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- The Leggett-Garg Inequality Macrorealism + Noninvasive Measurability
- 2 New types of Macrorealism:

Eigenpreparation Support vs Eigenpreparation Undermining Quantum mechanics must be Eigenpreparation Undermining

- O Noise-tolerant definition:
 - (α, β) -Support

Quantum Mechanics poses restrictions on (α, β)

Legget & Garg (1985)

- MR: "Macroscopic realism: A macroscopic system with two or more macroscopically distinct states available to it will at all times be in one or the other of these states."
 - \rightsquigarrow Some observable Q has a definite value at all times.
- **NIM:** "Noninvasive measurability at the macroscopic level: It is possible, in principle, to determine the state of the system with arbitrarily small perturbation on its subsequent dynamics."
 - → There are Q-measurements that do not alter the state of the system.

$MR \land NIM \land QM \implies \bot$

The Leggett-Garg Inequality 2/2



$$\begin{split} & \mathsf{MR:} \ -1 \leq \langle Q_1 Q_2 \rangle_{123} + \langle Q_2 Q_3 \rangle_{123} + \langle Q_1 Q_3 \rangle_{123} \leq 3, \\ & \mathsf{NIM:} \ -1 \leq \langle Q_1 Q_2 \rangle_{123} + \langle Q_2 Q_3 \rangle_{23} + \langle Q_1 Q_3 \rangle_{13} \leq 3. \end{split}$$

• The Leggett-Garg Inequality

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Eigenstate-Eigenvalue Link

Observable A has a definite value \iff The system is in an eigenstate for A.

$MR \land E-E Link \implies$ Superselection Rule

There are no superpositions for the macro-observable Q.

Nature, while known to tolerate linear superpositions at the atomic level, cannot tolerate quantum superpositions of macroscopically distinct states – Leggett 1988

$MR \land E\text{-}E \ Link \land QM \implies \bot$

- Very strong assumption
- Relies heavily on formalism of quantum mechanics

Operational Models and Ontic Models

Operational model $(\mathcal{P}, \mathcal{T}, \mathcal{M})$

 $P \in \mathcal{P}$ is a preparation,

 $T \in \mathcal{T}$ is a transformation, $M \in \mathcal{M}$ is a measurment,

 $\mathbb{P}(m|M, T, P)$ probability of outcome m for measurement M performed on a system prepared according to P and transformed according to T.

Ontic model (Λ,Π,Γ,Ξ)

 $\begin{array}{lll} \lambda \in \Lambda & \text{is an ontic state,} & \mu \in \Pi & \text{is a probability measure,} \\ \gamma \in \Gamma & \text{is a Markov kernel} & \xi \in \Xi & \text{is a Markov kernel} \\ & \text{from } \Lambda \text{ to } \Lambda & & \text{from } \Lambda \text{ to } \Omega_{\xi}. \end{array}$

 $\forall (P, T, M)$ there exists (μ_P, γ_T, ξ_M) such that

$$\mathbb{P}(m|M, T, P) = \int_{\Lambda} \int_{\Lambda} \xi_M(m|\lambda') \gamma_T(d\lambda'|\lambda) d\mu_P(\lambda).$$

Eigenstate-Eigenvalue Link

Observable A has a definite value \iff The system is in an eigenstate for A.

- Eigenstate \mapsto Eigenpreparation: $\mathbb{P}(q|Q, P_q) = 1$.
- Superselection rule → all preparations are convex combinations of eigenpreparations.
- MR \land QM \implies Superpositions introduce novel preparations.
- Do they also introduce novel ontic states?

Generalized Eigenstate-Eigenvalue Link

Observable A has a definite value \iff The system is in an ontic state in the support of an eigenpreparation for A.

Eigenpreparation Support vs Eigenpreparation Undermining

- Superpositions introduce novel preparations.
- Do they also introduce novel ontic states?

Generalized Eigenstate-Eigenvalue Link

Observable A has a definite value \iff The system is in an ontic state in the support of an eigenpreparation for A.



Maroney & Timspon (2016) arXiv:1412.6139

Quantum Mechanics is Eigenpreparation Undermining

Eigenpreparation support \implies All ontic states behave like eigenpreparations:

- $\mathbb{P}(a|A, P_q) = 0$, then $\mathbb{P}(a|A, P) \leq 1 \mathbb{P}(q|Q, P) \ \forall P$.
- $\mathbb{P}(a|A, T, P_q) = 0$, then $\mathbb{P}(a|A, T, P) \leq 1 \mathbb{P}(q|Q, P) \ \forall P$.



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- $\mathbb{P}(a|A, T, P_q) = 0$, then $\mathbb{P}(a|A, T, P) \leq 1 \mathbb{P}(q|Q, P) \ \forall P$.

Theorem

Q and A 3-valued observables, Q a macro-observale, eigenpreparation support, and

$$\mathbb{P}(a_2|A, P_{q_1}) = \mathbb{P}(a_3|A, T, P_{q_1}) = \mathbb{P}(q_3|Q, T, P_{q_1}) = 0,$$

then for every P

 $\mathbb{P}(q_1|Q,P) - \mathbb{P}(q_2|Q,T,P) - \mathbb{P}(a_1|A,T,P) \leq 0.$

$\mathsf{MR} \land \mathsf{ESupp} \land \mathsf{QM} \implies \bot$

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The Problem with Noise 1/2

The distinction between Eigenpreparation Supported and Eigenpreparation Undermining models is not noise-tolerant.



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then for every P

$$\mathbb{P}(q_1|Q,P) - \mathbb{P}(q_2|Q,T,P) - \mathbb{P}(a_1|A,T,P) \leq 0.$$

Not Noise-Tolerant



Eigenpreparation Support:

 $\exists \alpha \text{ s.t. } \int \min(f_P, \alpha f_q) \, \mathrm{d}\lambda = \mathbb{P}(q|Q, P)$ (α, β) -Support: $\beta + \int \min(f_P, \alpha f_q) d\lambda \ge \mathbb{P}(q|Q, P)$

- Eigenpreparation Support $\iff \beta = 0$,
- (α, β) -Support trivial for $\beta = 1$.

Noise-Tolerant Constraint on Macrorealism

Theorem

Q and *A* 3-valued observables, *Q* a macro-observale, eigenpreparation support, and

$$\mathbb{P}(a_2|A, P_{q_1}) = \mathbb{P}(a_3|A, T, P_{q_1}) = \mathbb{P}(q_3|Q, T, P_{q_1}) = 0,$$

then for every P

$$\mathbb{P}(q_1|Q,P) - \mathbb{P}(q_2|Q,T,P) - \mathbb{P}(a_1|A,T,P) \leq 0.$$

Theorem

Q and A 3-valued observables, Q a macro-observale, $(\alpha,\beta)\text{-support},$ then for every P

 $\mathbb{P}(q_1|Q,P) - \mathbb{P}(q_2|Q,T,P) - \mathbb{P}(a_1|A,T,P) \le \alpha \left(\mathbb{P}(a_2|A,P_{q_1}) + \mathbb{P}(a_3|A,T,P_{q_1}) + \mathbb{P}(q_3|Q,T,P_{q_1})\right) + 2\beta.$